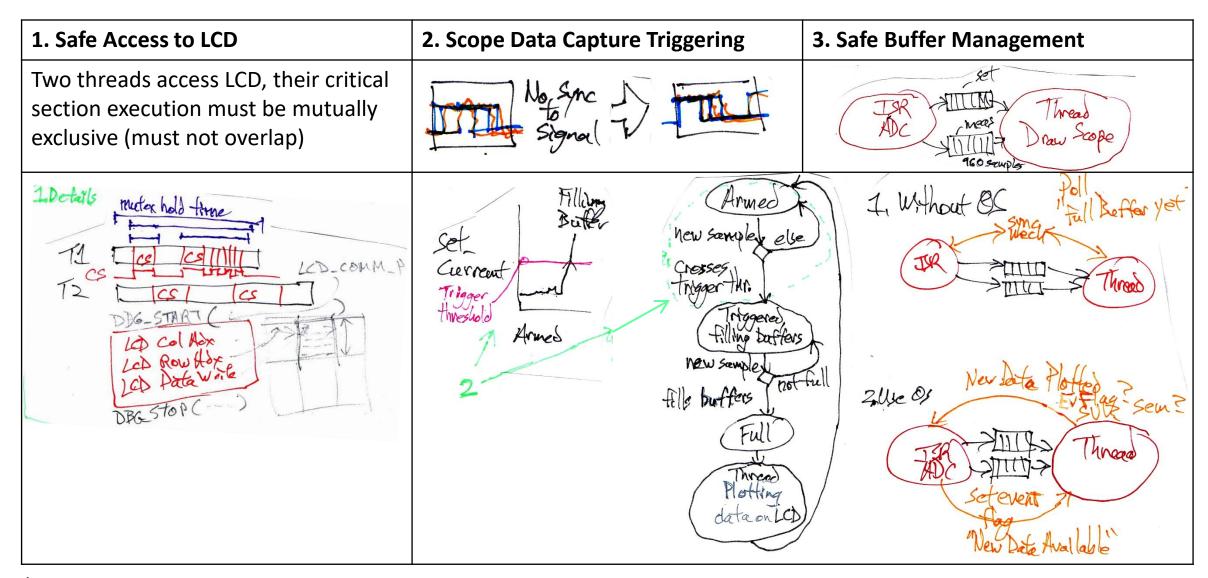
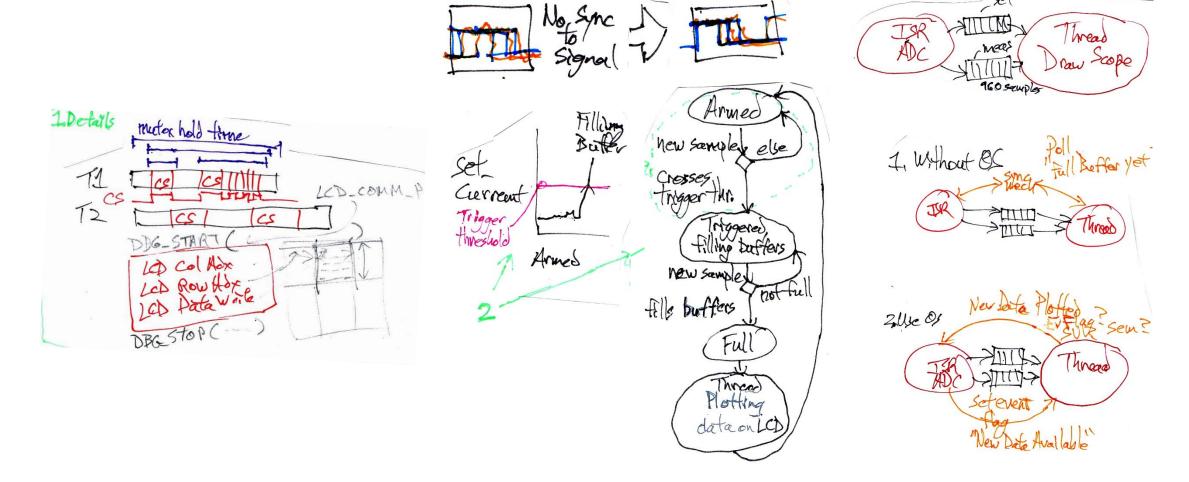
Synchronization in Project



Synchronization in Project



Buffer Synchronization using OS

```
ADC ISR (or a function it calls)
                                                                                         New Lata
static int recording = 0;
                                                                              2.Use 01
static int n = 0;
read I measured from ADC
r = osEventFlagsWait(...,ScopeArmed,...,0);
if (!(r & osFlagsError)) {
  // No error, so test for event
  if ((r == ScopeArmed) &&
      (I setpoint > trigger threshold)) {
                                                    ScopeArmed
    recording = 1;
                                                     Event Flag
    n = 0;
                                                                       Thread Draw Waveforms
                                                                       while (1) {
if (recording == 1) {
                                                                          osEventFlagsWait(...,BufFull,...,osWaitForever);
  save I_measured to measured_buffer[n]
                                                                          DrawWaveforms();
  save I setpoint to setpoint buffer[n]
                                                                          osEventFlagsSet(...,ScopeArmed);
  n++;
  if (n==BUFSIZE) {
                                                      BufFull
     recording = 0;
                                                    Event Flag
    osEventFlagsSet(...,BufFull);
Do normal control loop processing
```

Mutex for LCD Controller Access

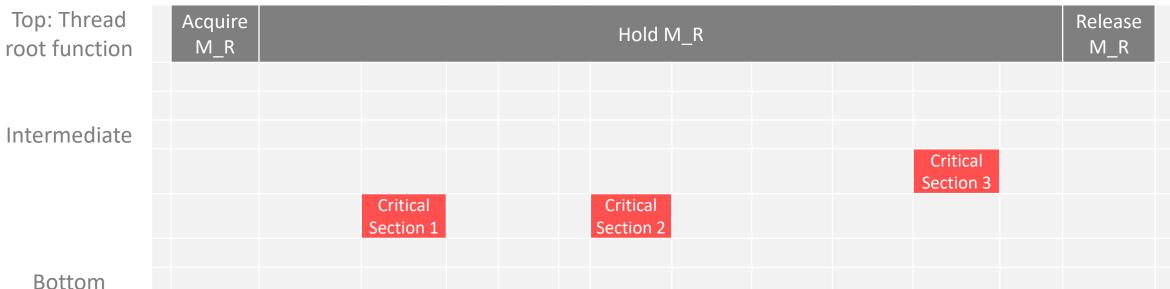
Critical Section Length, Blocking and Responsiveness

- Threads A, B access shared resource R, other threads C, D don't
- Access resource safely by protecting critical sections for R with mutex lock M_R
 - Threads A, B must acquire mutex M_R before starting critical section
 - Threads A, B must release mutex M_R after completing critical section

- If mutex not available, then thread blocks
 - Can monitor blocking activity on logic analyzer by adding debug output signal
 - Set before acquiring mutex, clear after acquiring mutex
 - Thread A, B holding mutex longer →
 - Longer possible blocking time for thread B, A = worse responsiveness for B, A
 - If C, D independent of A, B and R, then no impact on responsiveness for C, D

Critical Section Length, Blocking and Responsiveness

Code Level



- To get best responsiveness, acquire/release mutex immediately before/after each critical section
 - Hard! To do this, we need to know...
 - How many critical sections in each thread?
 - Where does each critical section start and end?
 - Finding critical sections in code requires analysis (thinking, development time)

- Start simple: at a high level
 - Protect all critical sections for R in thread by acquiring M_R before first critical section, releasing M_R after last critical section. Better safe than sorry.
 - Mutex held conservatively -- for longer than necessary
 - Mutex was probably acquired earlier than needed
 - If 2+ critical sections, mutex was held when not needed (between critical sections)
 - Mutex was probably released later than necessary

Reducing Blocking Time

Code Level

Top: Thread root function

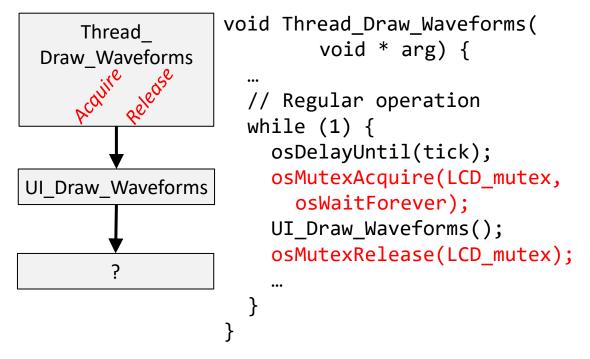
Intermediate

Bottom

Acquire M_R	Hold M_R		elease M_R	Acquire M_R Hold M_R	Release M_R
				Critical	
Crit	ical	Critical		Section 3	
Secti		Section 2			

- Analyze critical sections to be able to reduce mutex holding time
- Break mutex holding time into pieces
 - Release mutex after critical section, acquire before next critical section
- Hold for less time
 - Don't acquire so early, don't release so late

Example from Project

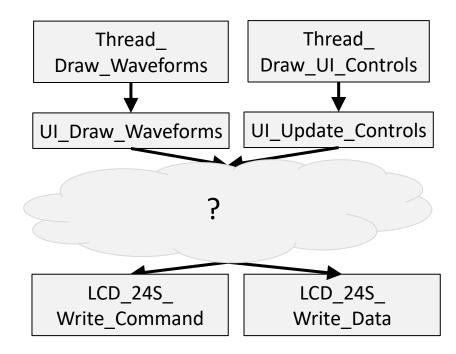


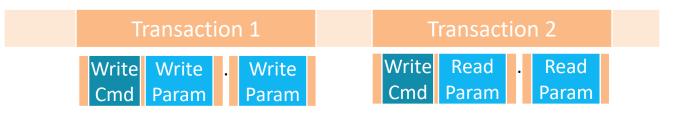
- LCD Controller interface
 - Used by two threads: Thread_Draw_Waveforms,
 Thread_Draw_UI_Controls
 - Want to protect with LCD_mutex

- Where should threads acquire and release LCD_mutex?
 - Depends on number, position and duration of critical sections
 - Easy first solution: in or near thread root function

Example from Project

- If mutex is held too long, responsiveness suffers, must improve
 - Look for code which may be a critical section or contain one (e.g. through subroutine calls).
- What does a critical section look like?
 - "Any code that talks to the LCD Controller"
- What does that look like? How does code talk to the LCD controller?
 - Functions to access GPIO-emulated LCD interface bus
 - LCD_24S_Write_[Command|Data]
 - (Read not implemented yet)
- LCD interface transactions
 - Two types
 - Write command, write optional data parameters
 - Write command, read optional data parameters

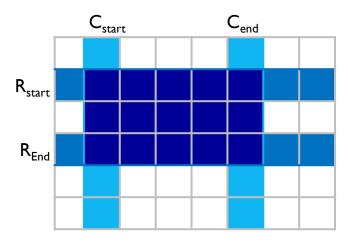




Draw a Filled Rectangle

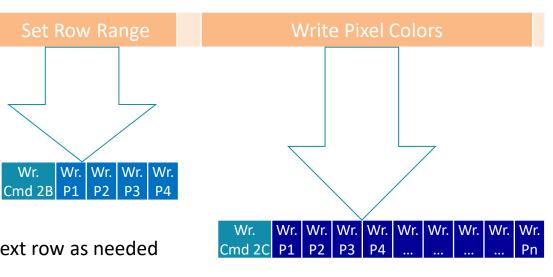
- Writing pixels to rectangle is fundamental operation
 - Many shapes are rectangles. Pixel: 1 x 1, rectangle: n x m, H line: n x 1, V line: 1 x n
 - Character? Rectangle with font bitmap selecting fore/background color per pixel
- LCD controller (ST7789) has H/W support for drawing rectangles quickly
 - "Fill this rectangle with these pixels from left to right, wrapping rows as needed."

LCD Ctlr. Frame Buffer Contents



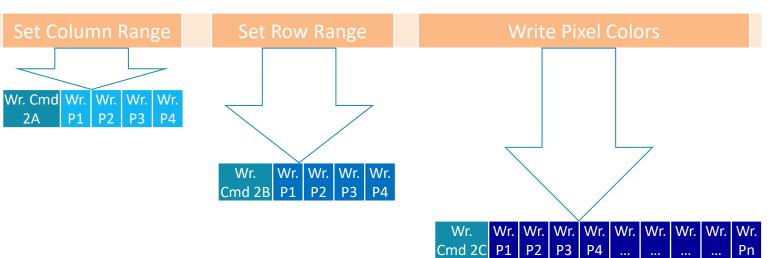
- LCD commands used
 - Column Address Set: CASET (0x2A)
 - Set column range in frame buffer to C_{start} (params P1:P2) to C_{End} (P3:P4)
 - Row Address Set: RASET (0x2B)
 - Set row (page) range in frame buffer to R_{Start} (P1:P2) to R_{End} (P3:P4)
 - Memory Write: RAMWR (0x2C)
 - Write the following pixel data items to that rectangle, wrapping to next row as needed

Wr. Cmd Wr. Wr. Wr. Wr.

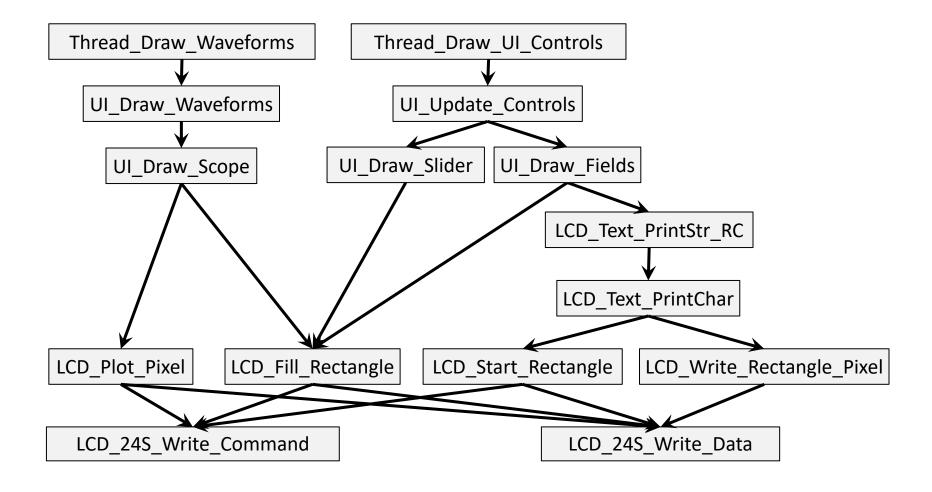


Code and Critical Section

- Example code for LCD transactions
 - Column Address Set: CASET (0x2A)
 - Row Address Set: RASET (0x2B)
 - Memory Write: RAMWR (0x2C)
- Critical section
 - Start?
 - End?



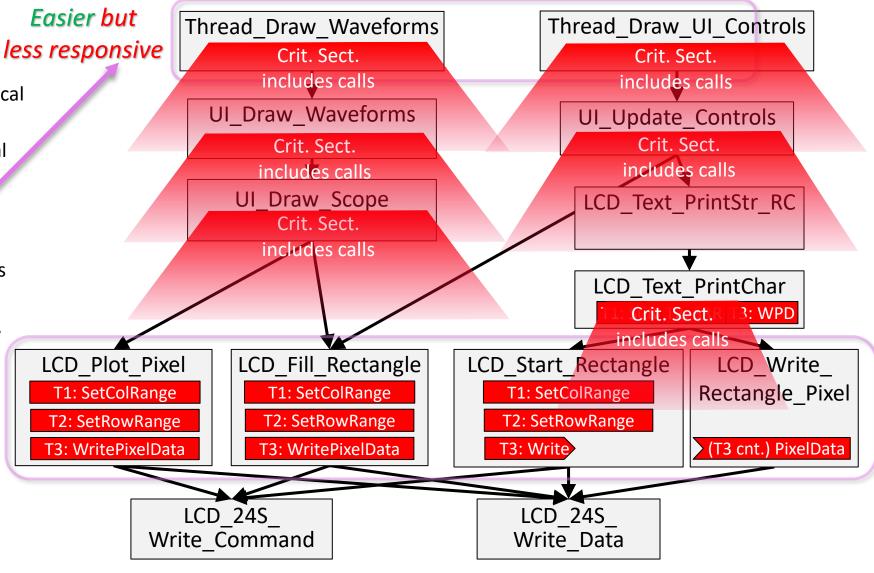
Gathered from Linker-generated Callgraph



Gathered from Linker-generated Callgraph

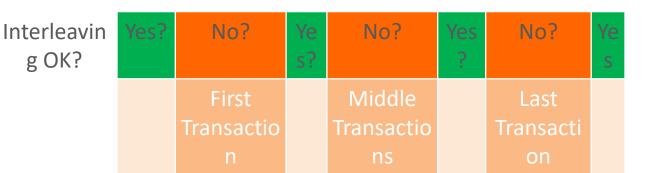
- Where to acquire mutex and release mutex?
 - Must acquire mutex before critical section starts
 - Must release mutex after critical section ends
- Trade-Offs
 - Higher up in call graph:
 easier, but longer blocking times
 - Lower in call graph: harder (requires more analysis), shorter blocking times

Harder but more responsive



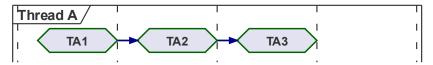
Is the Whole Transaction a Critical Section?

- OK to interleave critical sections ...
 - During a transaction?
 - Probably usually not OK, but...
 - ... maybe at very beginning or end, or special cases? Need to analyze code more.
 - Between transactions?
 - Probably usually **OK**, but ...
 - ... not when transactions from different threads affect shared state... meaning what? Examine LCD Controller example

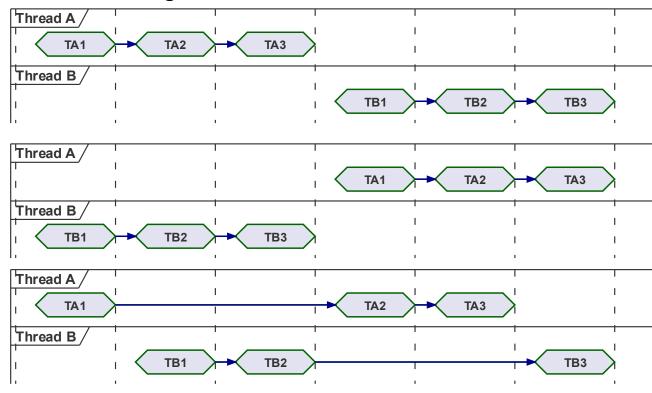


Transaction Ordering: General Case

Within Thread n, assume transactions Tn1, Tn2,
 Tn3 must be performed in order



- Does transaction ordering between different threads matter?
 - If not, we can interleave transactions arbitrarily, switching between threads without restrictions



Transaction Ordering: LCD Controller

- Does transaction ordering between different threads matter?
 - Depends on nature of interleaved transactions do they access shared state within the LCD Controller?
- Consider transactions to draw a rectangle (or pixel, character, horizontal/vertical line)
 - Transaction 1: Set Column Range in Frame Buffer
 - Transaction 2: Set Row Range in Frame Buffer
 - Transaction 3: Write Pixel Color Data to Frame Buffer

Critical Sections and LCD Code

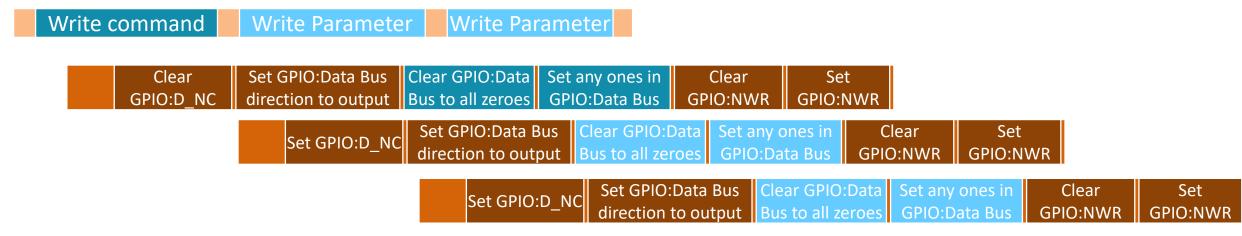
- Each transaction has a critical section.
 - Does critical section span entire transaction? Where does it start, end?

Interleaving OK?	(Mostly) Yes	No – Critical Section							(Mostly
	Prepare for transaction	Write command	Write Param	eter			Write Last Para	meter	
Preemption OK?	Yes or Mostly Yes	No – Critical Section						Υ	
	Prepare for transaction	Write command	Read Parameter			Read	Last Parameter		

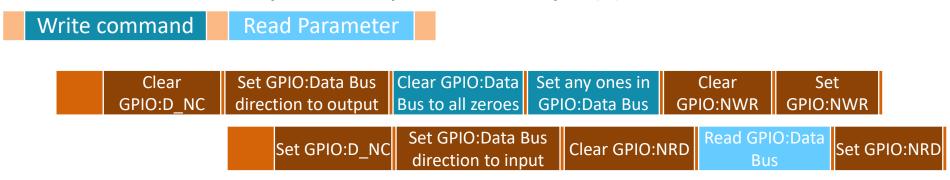
- Critical section:
 - Starts with writing command
 - Ends when last parameter has been read or written
- Which is the last parameter for a transaction?
 - Release mutex after that last parameter

Finer-Grain Concurrency for LCD Controller Interface?

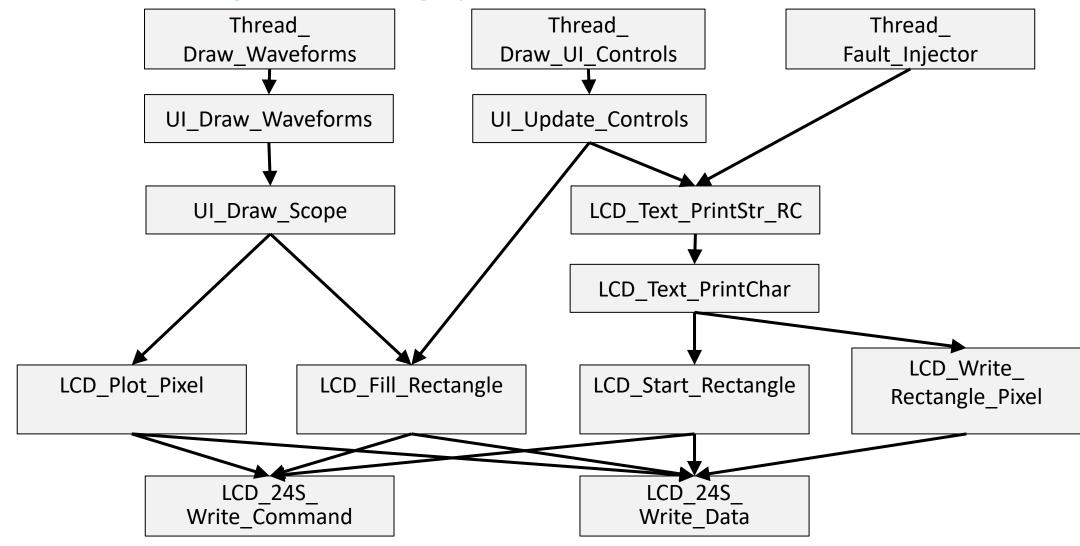
- Write to / read from the LCD controller by emulating a bus with GPIO
- Write command byte, write parameter byte(s)



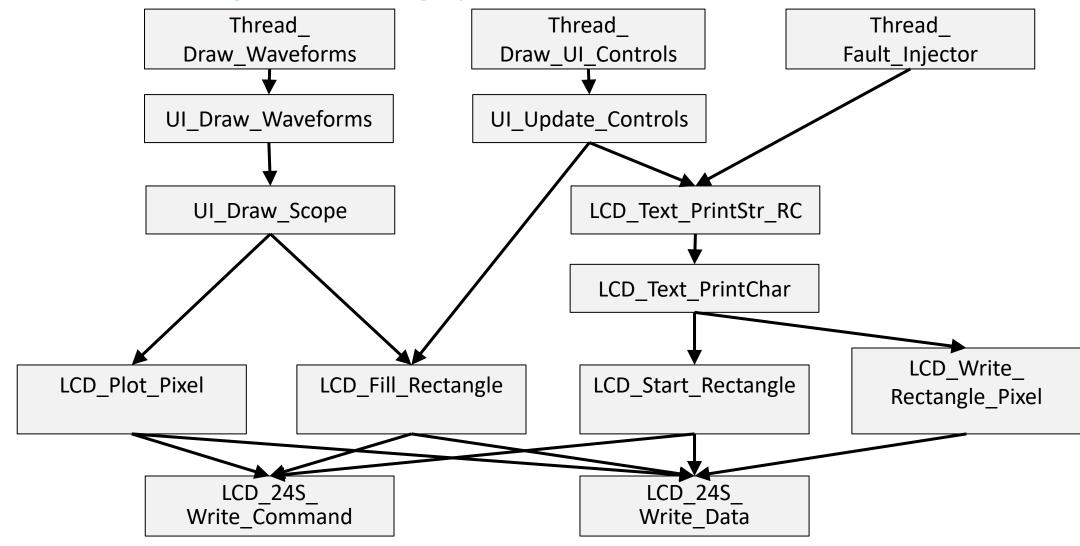
Write command byte, read parameter byte(s)



Gathered from Linker-generated Callgraph



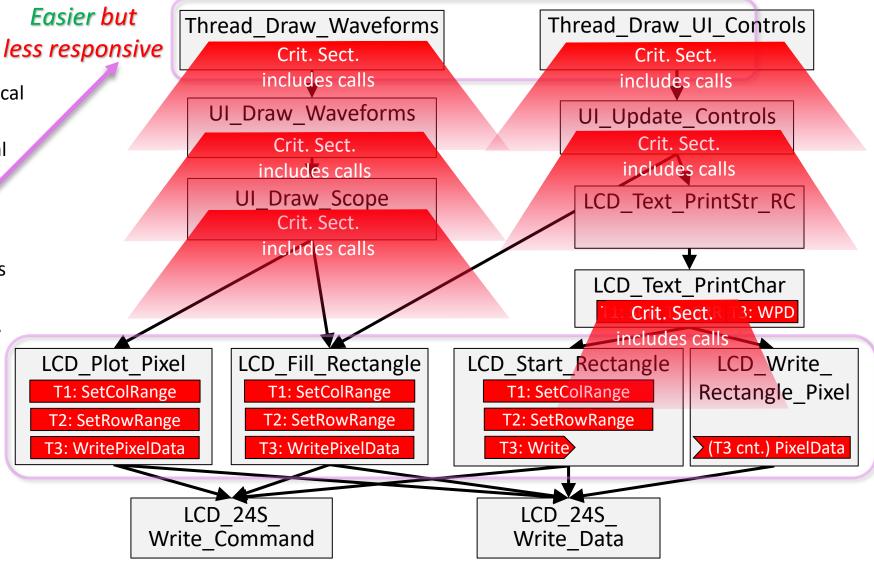
Gathered from Linker-generated Callgraph



Gathered from Linker-generated Callgraph

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Harder but more responsive



LCD Update Code

